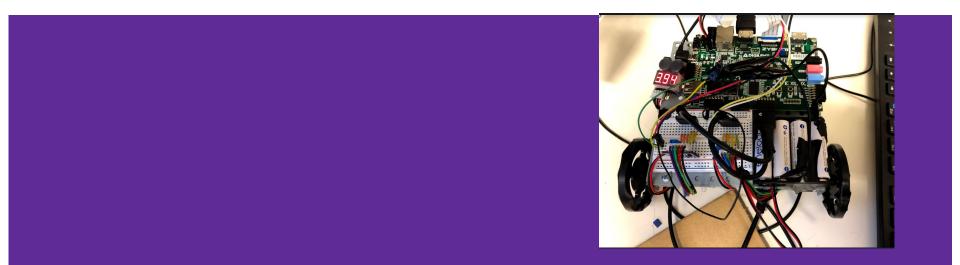
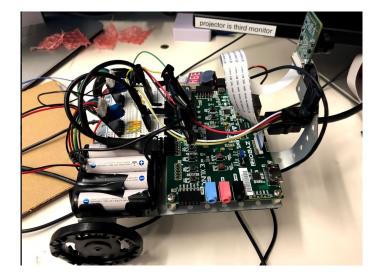
Robot Car

Yao Jiang Cheah, Raed Ibrahim, Joseph Ward

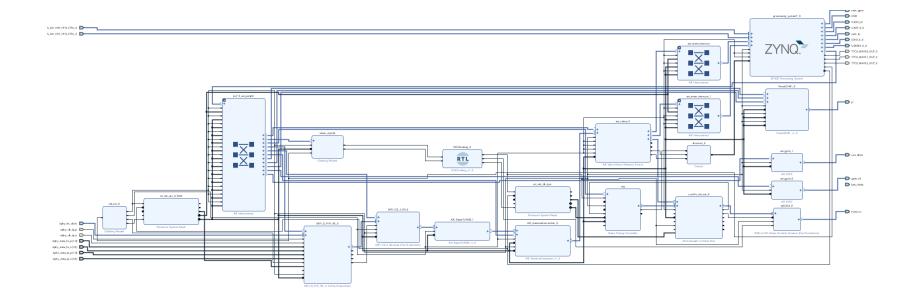


What is it?

- Remote controlled robot
- Send controls to drive
- Receive image from bot to navigate
- Can move left, right, forward, backwards



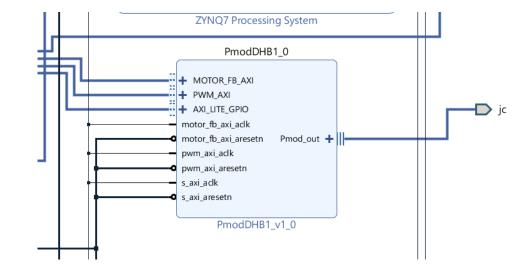
Overview of Hardware Pipeline



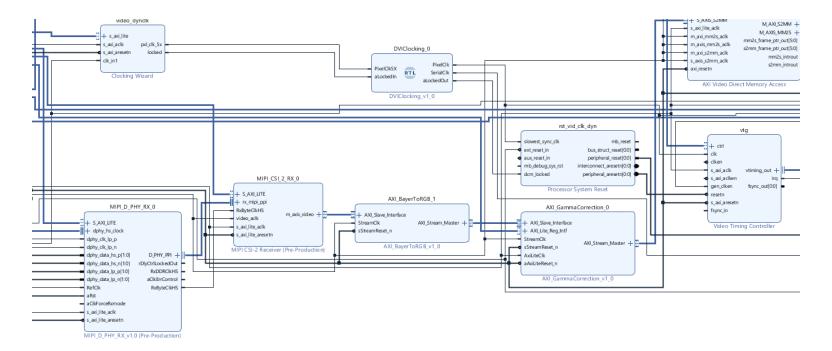
Online Resources Used

1-Zybo Z7 Pcam 5C Demo

2-Digilent Pmod IPs



Zybo Z7 Pcam 5C Pipeline (Modified for Z7 10)



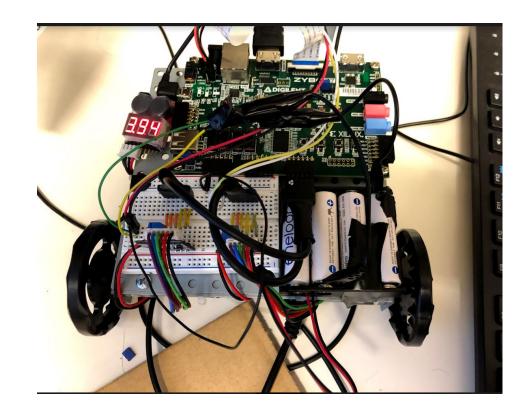
Challenges of Pcam Demo on Zybo Z7 10

- Original Demo used for Zybo Z7 20 Needs a lot more than 17,600 LUTs (about 18k-22k)
- Was able to reduce down to only using 8k+ LUTs

	Zybo Z7-10	Zybo Z7-20	
FPGA part	XC7Z010-1CLG400C	XC7Z020-1CLG400C	
1 MSPS On-chip ADC	Yes	Yes	
Look-up Tables (LUTs)	17,600	53,200	
Flip-flops	35,200	106,400	
Block RAM	270 KB	630 KB	
Clock Management Tiles	2	4	
Available Shield I/O	32	40	
Total Pmod Ports	5	6	
Fan Connector	No	Yes	
Zynq Heat Sink	No	Yes	
HDMI CEC Support	TX port only	TX and RX ports	
RGB LEDs	1	2	

What makes it work?

- Zybo Z7-10 fpga
- Pmod camera
- Motors hooked up to pmod
- ESP-01s wifi chip
 - Baudrate: 115200



Challenges

- Integrating different camera project with wifi and motor drivers
 - VHDL Wrapper wasn't updating
- Pmod camera IP cores had to be modified to fit on Zybo z710
- Powering the board with all the components
 - Too much power draw would cause the board to reset
 - Had to use seperate batteries for wifi
- Couldn't get wifi pmod to work
 - Had to use different wifi module
 - Video transmitted slower than we hoped

Rubric

Attributes	Performance			
Aundules	Low 25pts	Medium 50pts	High 75pts	
Controls	Robot is controllable in some form	Robot can be controlled remotely through wifi from zedboard	Robot can be controlled through wifi using android app	
Camera	Camera works	Camera streams video over wifi with low quality	Camera streams video with high quality	
User Interface	Video output to monitor Control through gpio	Video output to monitor control through	Video output to android app	
Demo and Report	Demo shows some parts working	Demo shows the full system working	Demo shows full system working and includes a clean overview of how everything works	